

**Amendments to the Claims:**

This listing of claims will replace all prior listings of claims in the application.

**Listing Of Claims:**

**Claim 1 (currently amended):** A control method for controlling an image pickup apparatus in an image delivery system that delivers ~~an image~~ images acquired from the image pickup apparatus to at least one of multiple external devices, the image pickup apparatus being remotely controllable by the multiple external devices, the method comprising:

controlling the image pickup apparatus at a preset time based on preset a schedule which includes one or more sets of control data to control the image pickup apparatus and a priority level of authorization to control the image pickup apparatus for each of the sets;

comparing, in a case where a request for remotely controlling the image pickup apparatus is received from one of the multiple external devices during the image pickup apparatus is controlled based on the schedule, a priority level of the requesting external device with the priority level of the set of control data used at the time when the request is received; and

inhibiting remote control of the image pickup apparatus by a predetermined the requesting external device during the control performed based on the control data if the priority level of the set of control data is higher than the priority level of the requesting external device as a comparison result.

**Claim 2 (currently amended):** The control method according to claim 1, wherein ~~each of the multiple external devices and the control data is given a priority level of authorization to control the image pickup apparatus, and upon the inhibiting of remote control, remote control of the image pickup apparatus by [[an]] the requesting external device with a is permitted if the priority level of the set of control data is lower than that of the control data is inhibited the priority level of the requesting external device as a comparison result.~~

**Claim 3 (canceled).**

**Claim 4 (currently amended):** The control method according to claim 2 further comprising forcibly stopping control performed based on ~~the control data when remote control of the image pickup apparatus is requested by an external device with a~~ the schedule if the priority level of the requesting external device is higher than that of the control data during the control performed based on the control data the priority level of the set of control data as a comparison result.

**Claim 5 (canceled).**

**Claim 6 (original):** The control method according to claim 1 further comprising:  
  
detecting presence of an abnormality based on an image acquired from the image pickup apparatus during the control performed based on the control data; and  
  
saving the image acquired from the image pickup apparatus when any abnormality is detected.

**Claim 7 (original):** The control method according to claim 6, wherein an abnormality is detected based on difference between frames of the image.

**Claim 8 (original):** The control method according to claim 1, wherein the control data includes at least one of a zoom value, a pan control value and a tilt control value of the image pickup apparatus.

**Claim 9 (currently amended):** The control method according to claim 1, wherein [[an]] a tracking operation is performed for an object moving [[in]] in an image acquired from the image pickup apparatus during the control performed based on the control data.

**Claim 10 (currently amended):** An image delivery apparatus that delivers images acquired from an image pickup apparatus to at least one of multiple external devices, the image pickup apparatus being remotely controllable by the multiple external devices, the image delivery apparatus comprising:

a data storage medium that stores a schedule which includes one or more sets of control data to control the image pickup apparatus and a start time to start control using the control data a priority level of authorization to control the image pickup apparatus for each of the sets;

a schedule execution unit that starts control of the image pickup apparatus based on the control data at the start time the schedule;

a comparison unit that compares, in a case where a request for remotely controlling the image pickup apparatus is received from one of the multiple external devices during the image pickup apparatus is controlled based on the schedule, a priority level of the requesting external device with the priority level of the set of control data used at the time when the request is received; and

a restriction unit that inhibits remote control of the image pickup apparatus by a predetermined the requesting external device during control by said schedule execution unit if the priority level of the set of control data is higher than the priority level of the requesting external device as a comparison result.

**Claim 11 (currently amended):** The image delivery apparatus according to claim 10, wherein ~~each of the multiple external devices and the control data is given a priority level of authorization to control the image pickup apparatus, and~~ said restriction unit inhibits does not inhibit remote control of the image pickup apparatus by the requesting external devices with a device if the priority level of the set of control data is of the set of control data is lower than that of the control data the priority level of the requesting external device as a comparison result.

**Claim 12 (canceled).**

**Claim 13 (currently amended):** The image delivery apparatus according to claim 11 further comprising a unit that forcibly stops control by said schedule execution unit ~~when remote control of the image pickup apparatus is requested by an external device with a~~ if the priority level of the requesting external device is higher than [that of the control data during control by said schedule execution unit the priority level of the set of control data as a comparison result.

**Claim 14 (canceled).**

**Claim 15 (original):** The image delivery apparatus according to claim 10, further comprising:

a detection unit that detects presence of an abnormality based on an image acquired from the image pickup apparatus during control by said schedule execution unit; and

a saving unit that saves the image acquired from the image pickup apparatus when any abnormality is detected by said detection unit.

**Claim 16 (currently amended):** The image delivery apparatus according to claim 15, wherein said detection means unit detects an abnormality based on difference between frames of the image.

**Claim 17 (original):** The image delivery apparatus according to claim 10, wherein the control data includes at least one of a zoom value, a pan control value and a tilt control value of the image pickup apparatus.

**Claim 18 (currently amended):** The image delivery apparatus according to claim 10, wherein [[an]] a tracking operation is performed for an object moving in an image acquired from the image pickup apparatus during control by said schedule execution unit.

**Claim 19 (original):** A storage medium readable by a data processing apparatus, the storage medium storing a program which is executable by the data processing apparatus and comprises program codes realizing a control method described in claim 1.

**Claim 20 (original):** A storage medium readable by a data processing apparatus, the storage medium storing a program which is executable by the data processing apparatus and comprises program codes which causes the data processing apparatus to function as an image delivery apparatus described in claim 10.